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The invention relates to a method for adjusting the control parameters (PA, K1..Kn) of a status controller (ZRB) which forms a closed-loop control circuit (R) in conjunction with a controlled system. The control parameters (PA, K1..Kn) can only be modified in such a way that when the pole positions (P1..P5) of the closed-loop control circuit (R) are represented in a complex frequency range plane (SE, IM, RE) said adjustment causes the pole positions (P1..P5) to be displaced in an approximate manner along a semi-circular (K) and/or original beam (A1, A3) path. One of the advantages of the invention is that the inventive method enables the control parameters (PA, K1..n) of the status controller (ZRB) to be adjusted by pre-selecting clear technical adjustment parameters such as overshoot factor (σ), settling time (μ) or adjustment time (t).